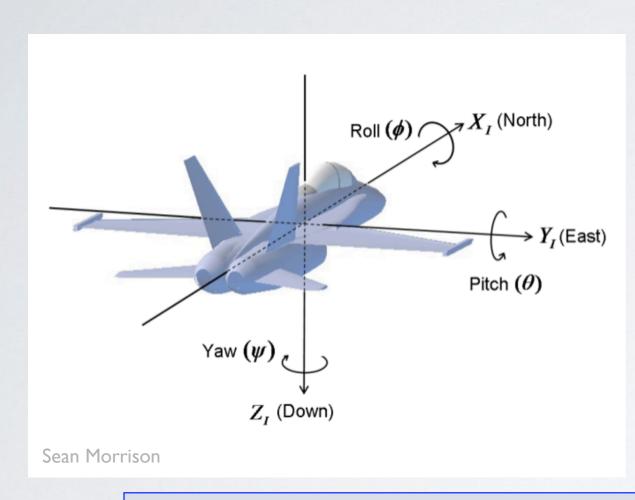
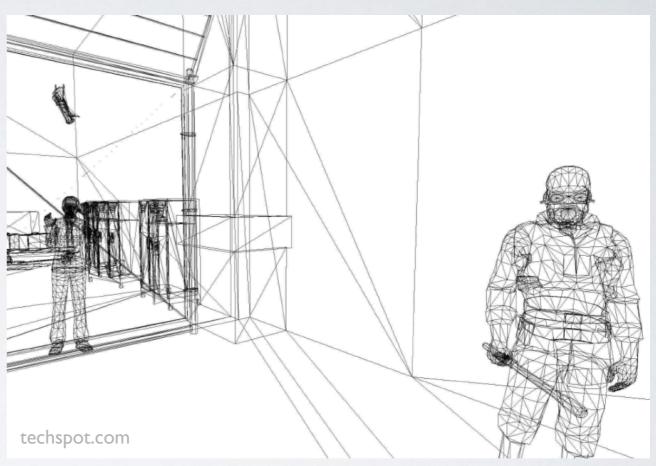
# Week 4 - #1 Linear Algebra (IV)





Today: Ch 3

Next Class: Ch 3, 10.1-10.4

### Ji-hoon Kim (Seoul National University)

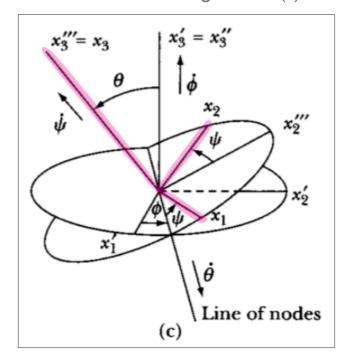
#### Rudimentary Mathematical Methods of Physics (Fall 2025): Quiz #5

— [open book and open note, "and" cellphone or laptop, drop it off as you leave the class ] —

Please write down your name and student ID in the top right corner. (0.0 pt: no paper found with your name / 0.5 pt: paper found with your name and some answers / 1.0 pt: good answers)

- 1. Boas, Chapter 3, Section 8, Problem 25
- 2. Boas, Chapter 3, Section 10, Problem 5(b)
- 3. Define "conic section" that appears at the beginning of Boas Chapter 3, Section 12.

Thornton & Marion, Figure 11-9(c)



The Euler angles are a classical way to specify the orientation of an object in space with respect to a fixed set of coordinate axes. This Demonstration shows two of the several implementations of the Euler angles (\$\theta\$, \$\theta\$, \$\theta\$). The initial (\$x\$, \$y\$, \$z\$) axes are indicated by the red, green, and blue arrows, while the final (\$x', \$y', \$z') axes are indicated by the red, green, and blue spheres.

Wolfram Demonstrations Project

**Euler Angles** 

demonstrations.wolfram.com/ EulerAngles/

# Rudimentary Mathematical Methods of Physics (Fall 2025): Suggested Problems in Chapter 3, Boas, 3rd ed.

The problems I suggest you to take a deeper look into include, but are not limited to, the following. The class homework assignments will mainly be from this list.

- Section 02: Problems 8, 13, 14, 17, 18
- Section 03: Problems 2, 6, 9, 10, 13, 15
- Section 04: Problems 5, 6, 9, 21, 23
- Section 05: Problems 17, 21, 32, 36, 42
- Section 06: Problems 6, 7, 16, 18, 21, 29, 30
- Section 07: Problems 12, 27, 31, 34, 35
- Section 08: Problems 2, 10, 15, 16, 17, 24
- Section 09: Problems 3, 5, 10, 17, 19(c), 24, 25(a)(b)
- Section 10: Problems 4(c), 5(a), 7
- Section 11: Problems 9, 10, 19, 21, 31, 33, 42, 44, 50, 57, 60, 61
- Section 12: Problems 9 (for Problems 4, 7), 16, 21
- Section 13: Problems 1, 4, 7
- Section 14: Problems 13

#### Chapter 10, Sections 1-4

- Section 02: Problems 6
- Section 03: Problems 1, 2, 8
- Section 04: Problems 2, 6, 8

# Rudimentary Mathematical Methods of Physics (Fall 2025): Suggested Problems in Chapter 4, Boas, 3rd ed.

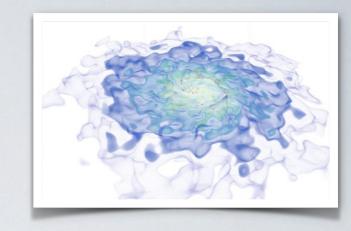
The problems I suggest you to take a deeper look into include, but are not limited to, the following. The class homework assignments will mainly be from this list.

- Section 01: Problems 7, 8, 9, 15, 16
- Section 02: Problems 1, 2, 3
- Section 04: Problems 2, 3, 7, 15
- Section 05: Problems 1, 2, 6, 8
- Section 06: Problems 1, 4, 9
- Section 07: Problems 2, 4, 7, 10, 16, 25, 28
- Section 08: Problems 2, 8, 11, 13
- Section 09: Problems 2, 5, 9, 11
- Section 10: Problems 2, 5, 10, 14
- Section 11: Problems 1, 4, 6, 7, 8
- Section 12: Problems 2, 5, 10, 13, 16, 19
- Section 13: Problems 6, 9, 16, 27, 29

# Rudimentary Mathematical Methods of Physics (Fall 2025): Suggested Problems in Chapter 5, Boas, 3rd ed.

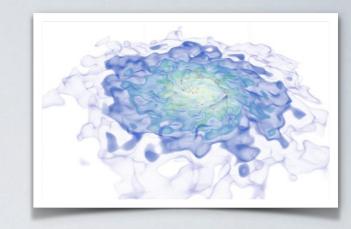
The problems I suggest you to take a deeper look into include, but are not limited to, the following. The class homework assignments will mainly be from this list.

- Section 01: Problems 2, 4, 5
- Section 02: Problems 3, 5, 9, 11, 13, 16, 20, 22, 26, 39, 41
- Section 03: Problems 6, 12, 13, 17, 18, 19, 20, 21, 25
- Section 04: Problems 2, 4, 7, 14, 16, 19, 20
- Section 05: Problems 1, 5
- Section 06: Problems 4, 6, 11, 18, 23, 25, 27



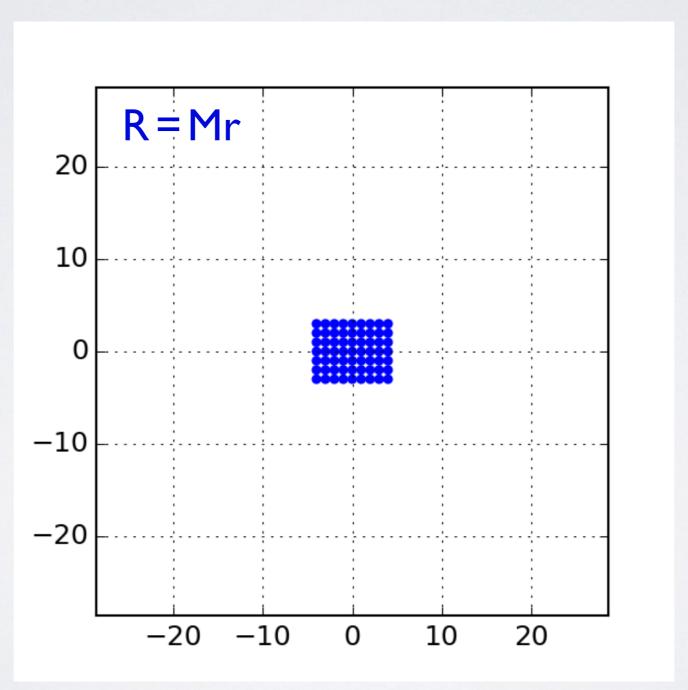
# HW #1 score and the grading criteria will be posted soon!

(Grader TA this time: 정은우, cewgenius@snu.ac.kr)

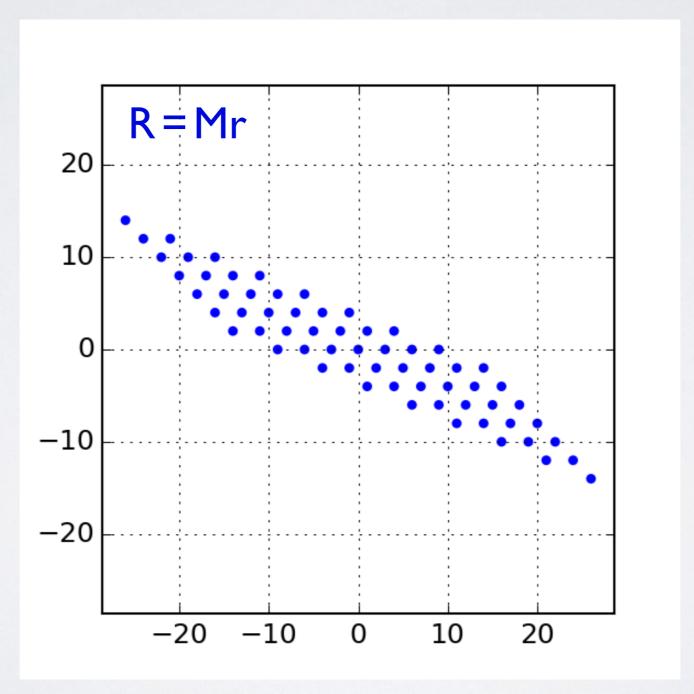


# Meaning of Diagonalization

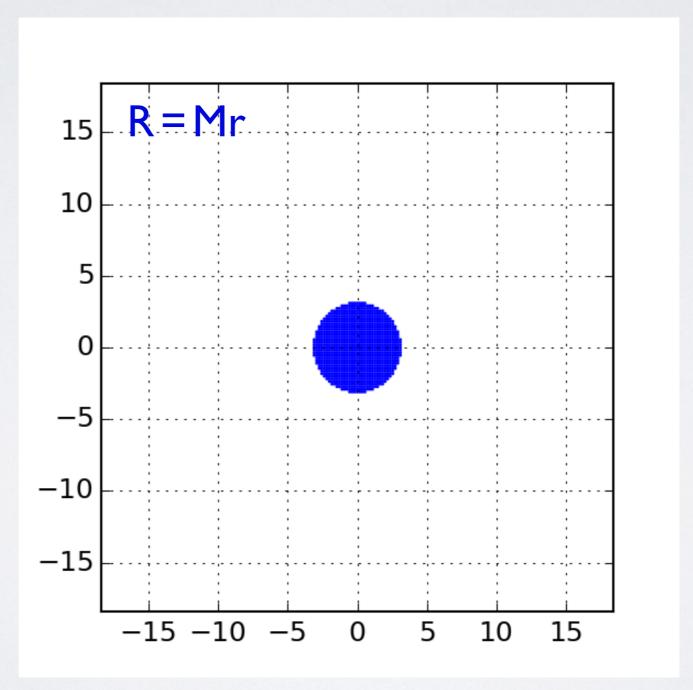
 Matrix C changes the old set of coordinate axes (x, y) to a new, convenient set of coordinate axes (x', y').



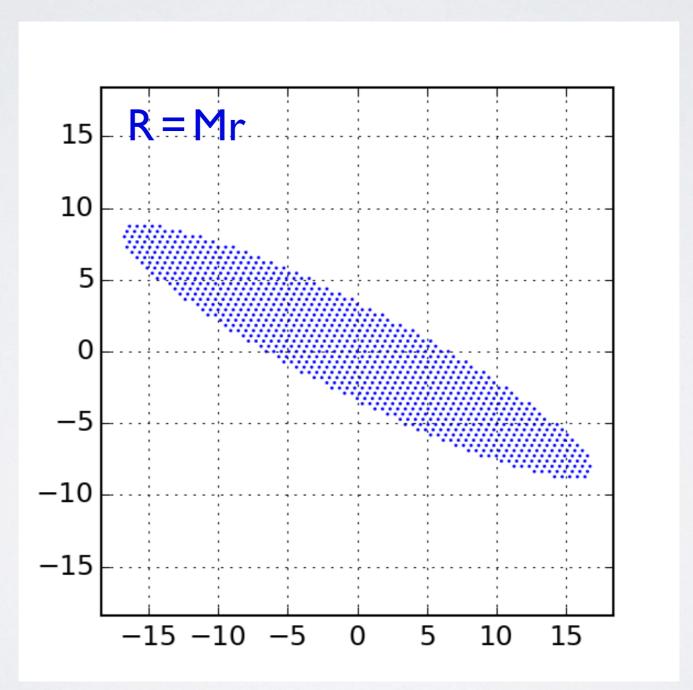
 Matrix C changes the old set of coordinate axes (x, y) to a new, convenient set of coordinate axes (x', y').



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